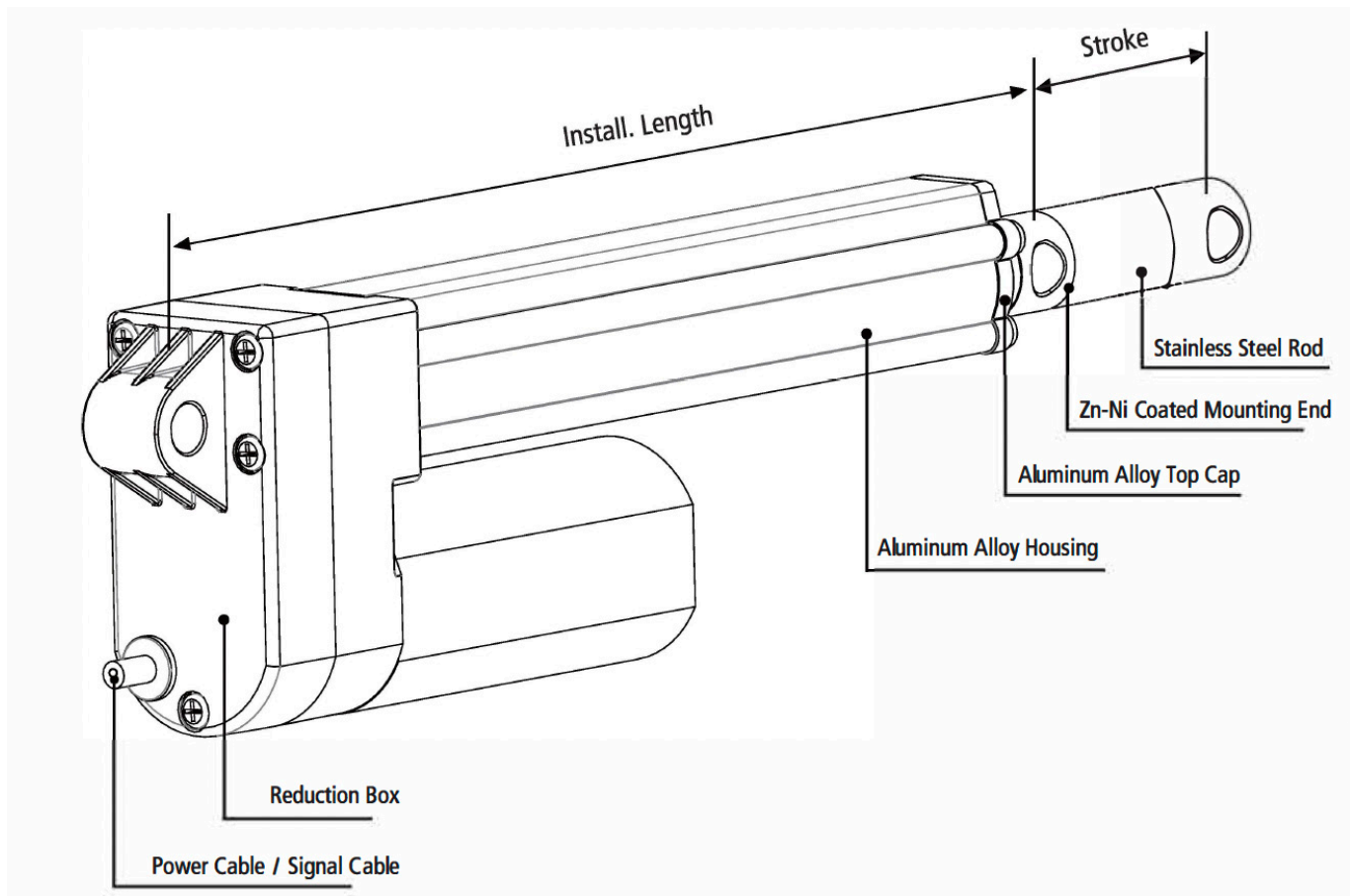


MLA-J2 Industrial Linear Actuator

2026 Catalog




• Glossary of Terms



| | |
|---------------------|---|
| Stroke | How far the rod extends outwards from the body. The difference between fully extended length and fully retracted length. (Customizable) |
| Installation Length | The length of unit when fully closed. (Customizable) |
| Front Mounting End | Optional. |
| Rear Mounting End | Optional. |
| Mounting Holes | Can be rotated by 90°. |
| Dynamic Force | The max. force the actuator can carry while it is moving. |
| Self-locking | The max. force the actuator can hold when it is stopped. |
| Weather Protection | IPXX. The first digit: Dust Protection. The Second Digit: Liquids Protection. Please refer to [Table 1.] |
| Duty Cycle | Continuous working time "a", rest time "b". Duty Cycle is $a/(a+b) \times 100\%$. Please refer to [Table 1.] |
| Speed | Includes free-load speed and full load speed. |
| Hall Sensor | Provides pulse signals. Displacement measurement is achieved through pulse counting, and the phase difference of the waveform can be used to identify the rotation direction of motor. Check [Table 1] to see if it is available. |
| Potentiometer | Potentiometer is a three-terminal variable resistor with a rotating contact which is used to measure the displacement of actuators. Check [Table 1] to see if it is available. |
| Manual Override | Can be used to extend or retract the actuator when there is no power in an emergency situation. Check [Table 1] for availability. |

• General Specifications

| | | | | | | | | | |
|----------------------------|---|--|---|--|--|---|--------------------------------------|-----------------------------------|-----------------------------------|
| Color | <input checked="" type="checkbox"/> Silver | <input type="checkbox"/> Black | <input type="checkbox"/> Custom |  | | | | | |
| Lead Screw | <input checked="" type="checkbox"/> Acme Screw | <input type="checkbox"/> Ball Screw | | | | | | | |
| Operation Mode | <input checked="" type="checkbox"/> Electrical | <input type="checkbox"/> Electrical + Manual | | | | | | | |
| Application | <input checked="" type="checkbox"/> Industrial | <input checked="" type="checkbox"/> Furniture | <input checked="" type="checkbox"/> Medical | | | | | | |
| Operational Temp. | <input type="checkbox"/> 5°C to 40°C | <input checked="" type="checkbox"/> -10°C to 65°C | <input checked="" type="checkbox"/> -40°C to 65°C | | | | | | |
| Operating Noise | <input checked="" type="checkbox"/> ≤45dB | <input type="checkbox"/> ≤50dB | <input type="checkbox"/> ≤65dB | | | | | | |
| Stroke Range | <input checked="" type="checkbox"/> 50 to 600mm | <input type="checkbox"/> 600 to 1,000mm | | | | | | | |
| Dynamic Load | <input type="checkbox"/> ≤1,200N | <input checked="" type="checkbox"/> ≤2,000N | <input type="checkbox"/> ≤4,000N | | | | <input type="checkbox"/> ≤10,000N | <input type="checkbox"/> ≤12,000N | <input type="checkbox"/> ≤20,000N |
| Duty Cycle | <input type="checkbox"/> 10% | <input checked="" type="checkbox"/> 20%* | <input type="checkbox"/> 25% | | | | <input type="checkbox"/> ≤50% | <input type="checkbox"/> 100% | |
| Motor Type | <input checked="" type="checkbox"/> Brushed DC | <input type="checkbox"/> Stepper Motor | <input type="checkbox"/> Brushless | | | | <input type="checkbox"/> Servo Motor | | |
| Overload Protection | <input checked="" type="checkbox"/> None | <input type="checkbox"/> Clutch | <input type="checkbox"/> Electronic | <input type="checkbox"/> Thermistor | | | | | |
| Weather Protection | <input type="checkbox"/> IP20 | <input type="checkbox"/> IP43 | <input type="checkbox"/> IP54 | <input type="checkbox"/> IP65 | <input checked="" type="checkbox"/> IP66 | <input type="checkbox"/> IP69K | | | |
| Position Feedback | <input checked="" type="checkbox"/> None | <input checked="" type="checkbox"/> Endstop Signal | <input checked="" type="checkbox"/> Hall Sensor | <input type="checkbox"/> Potentiometer | <input type="checkbox"/> Encoder | <input checked="" type="checkbox"/> Reed Switches | | | |
| Input Voltage | <input checked="" type="checkbox"/> 12VDC | <input checked="" type="checkbox"/> 24VDC | <input checked="" type="checkbox"/> 36VDC | <input checked="" type="checkbox"/> 48VDC | <input type="checkbox"/> 110VAC | <input type="checkbox"/> 220VAC | | | |

*Note: Do not exceed 4 minutes continuous working at full load at 20°C ambient temperature.

[Table 1]

Options for MLA-J2 Available Other Models

• Technical Parameters

| Code | Max. Dynamic Load (*See Note 2) | Max. Self-Locking Load | Reduction Ratio | Pitch (mm) | Speed +/-10% (mm/sec) (*See Note 1) | | Max. Stroke (*See Note 3) |
|------|------------------------------------|------------------------|-----------------|---------------|--|-----------|------------------------------|
| | (N) | (N) | | | Free Load | Full Load | (mm) |
| A | 2,000 | 3,000 | 32.6:1 | 3.17 | 6 | 5 | 600 |
| B | 1,500 | 2,500 | 32.6:1 | 5 | 10 | 7 | 600 |
| C | 1,000 | 1,500 | 32.6:1 | 7.5 | 15 | 11 | 600 |

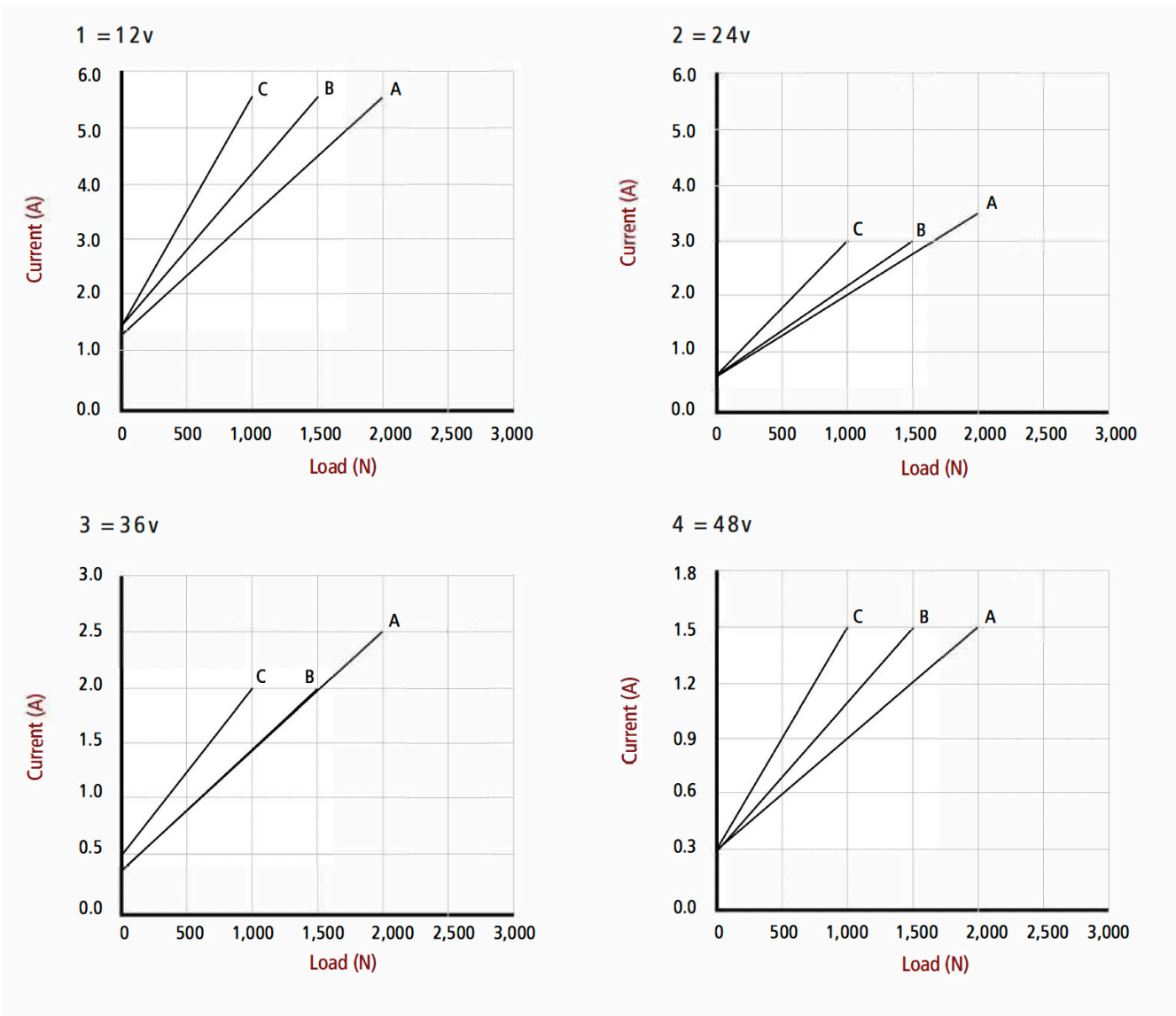
[Table 2]

*Notes:

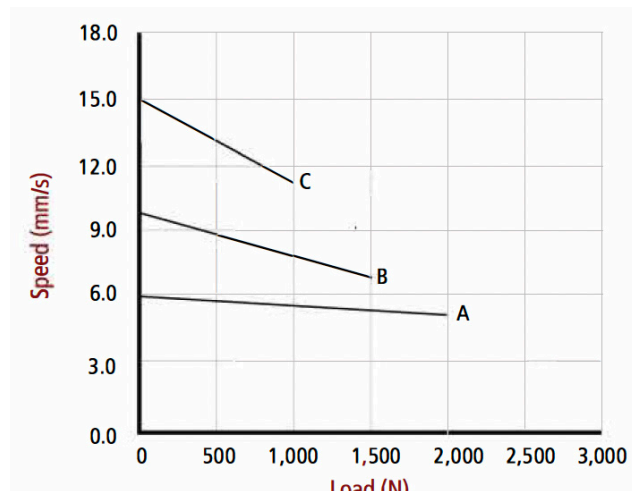
1. Measurements are made with actuators in connection with stable power supplies and ambient temperature of 20°C.
2. For example, when real load is 1,400N, choosing code "B" is recommended. You can also choose "A", which comes with an increased load buffer, higher safety factors, and extended product service time.
3. Many factors affect the "Customizable Maximum Stroke," such as load, speed, and direction of force. Actual application scenarios should be considered. Please contact cs@machmo.com if your required parameters are not listed.

• Performance

Current vs. Load



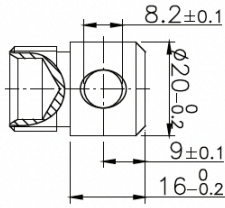
Speed vs. Load



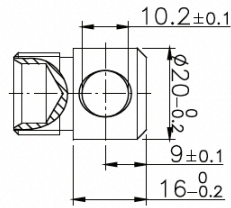
* Note: Measurements are made with Actuators in Connection with Stable Power Supplies and Ambient Temperature of 20°C.

•Front Mounting End

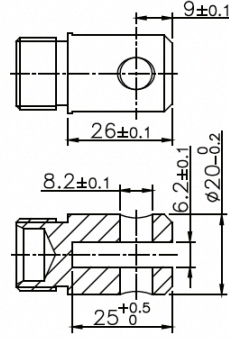
1. Please contact cs@machmo.com if none of the options below meet your requirements.



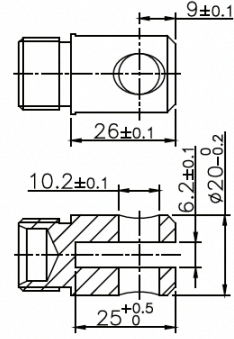
F01



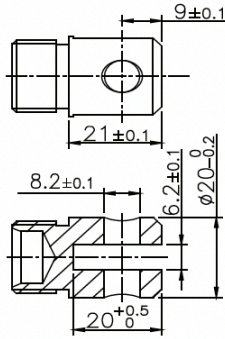
F02



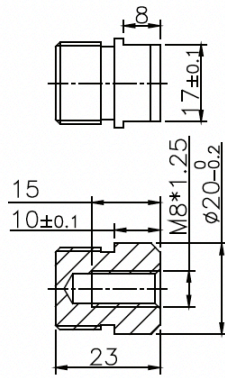
F03



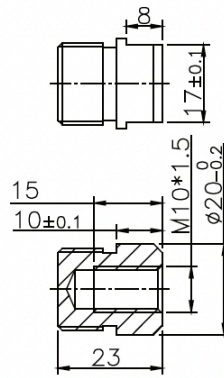
F04



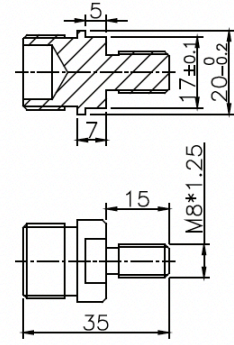
F05



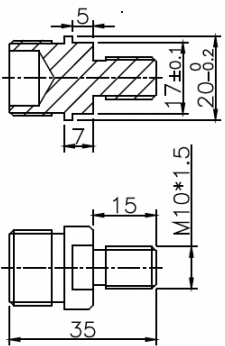
F06



F07

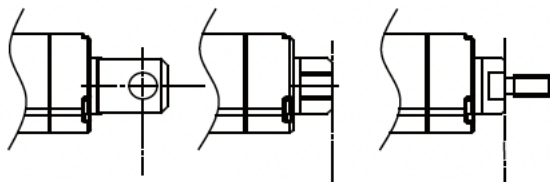


F08

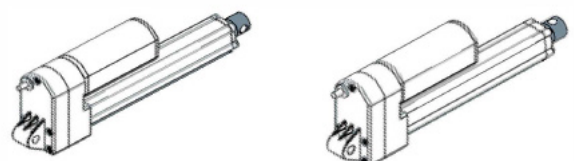


F09

2. Start of Installation Length



3. Hole Directions

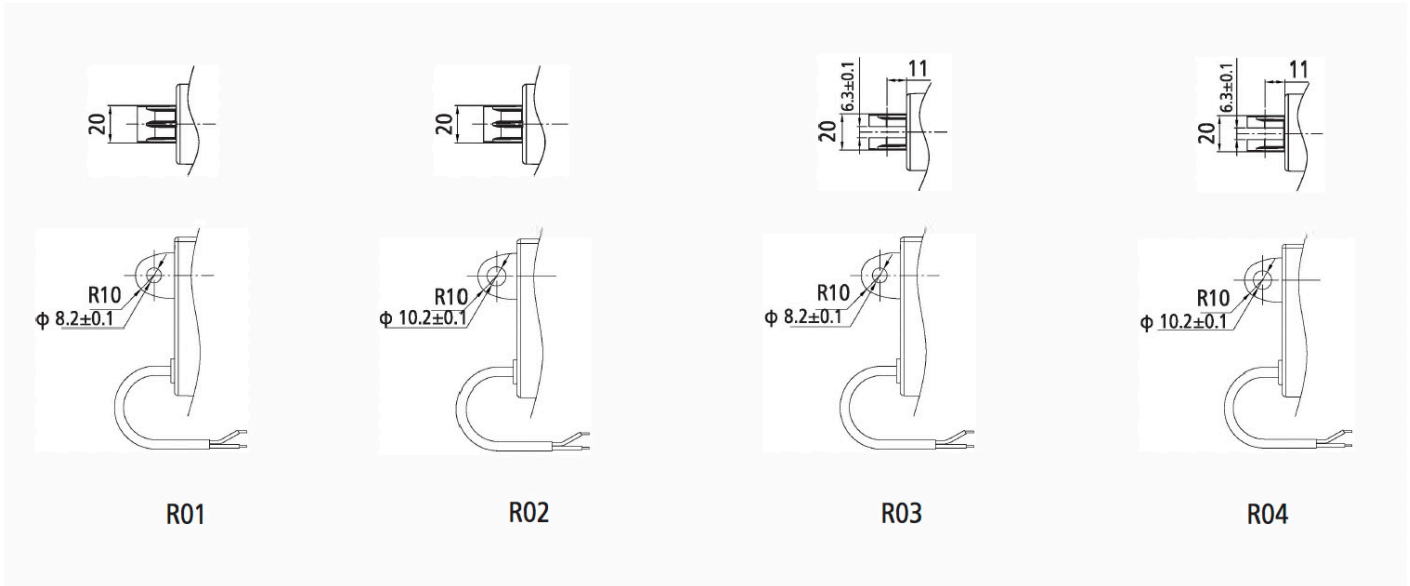


1 = 90°

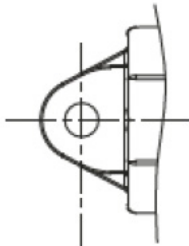
2 = 0°

• Rear Mounting End

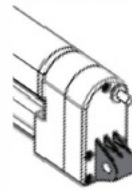
1. Please contact cs@machmo.com if none of the options below meet your requirements.



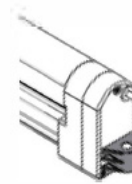
2. End of Installation Length



3. Hole Directions



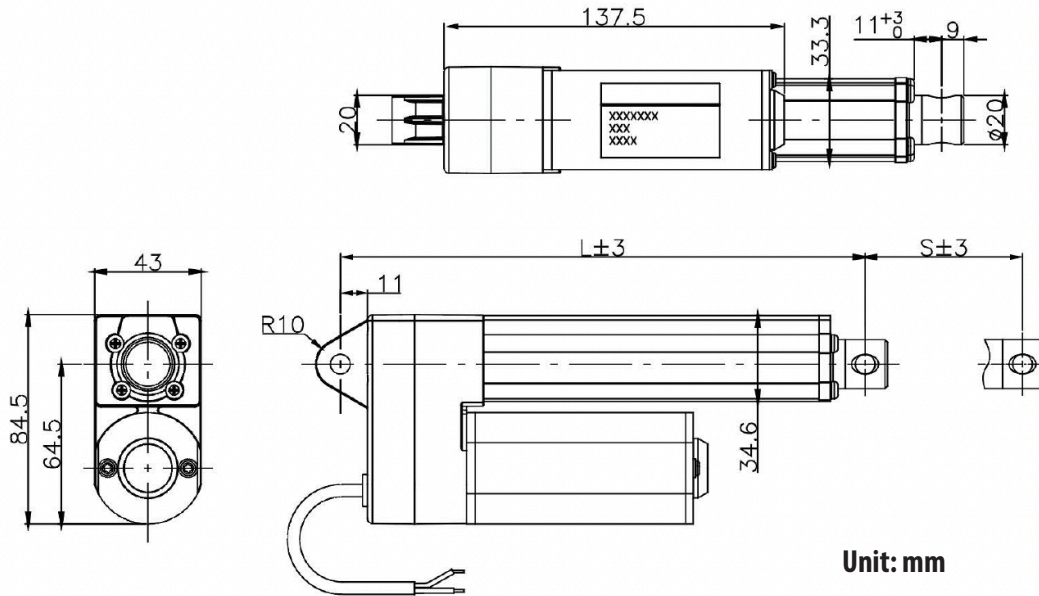
1 = 90°



2 = 0°

*Not applied to R01 & R02

• Product Dimensions



A. Mounting Ends VS. Installation Length

| | |
|---------------------|-------------------------|
| Front Mounting Ends | Rear Mounting Ends |
| | R01-R04 |
| F01, F02, F05-F09 | $A \geq S+115\text{mm}$ |
| F03, F04 | $A \geq S+123\text{mm}$ |

[Table 3]

B. Stroke VS. Installation Length

| Stroke (S) (mm) | Installation Length (L) (mm) |
|-----------------|------------------------------|
| 30 - 299 | + 0 |
| 300 - 499 | + 30 |
| ≥ 500 | + 60 |

[Table 4]

C. Reed Switch

| Reed Switch | Installation Length (L) (mm) |
|-------------|------------------------------|
| Optional | + 10 |

[Table 5]

How to Calculate "Installation Length": Example:

S = Stroke, L = Installation Length
 $L \geq A + B + C$

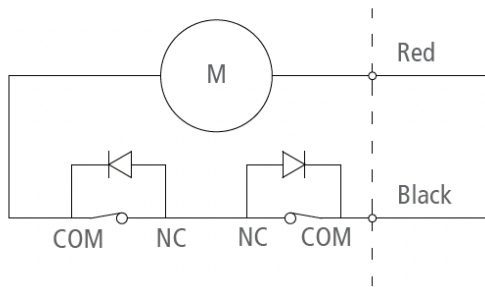
| Front Mount | Rear Mount | S (mm) | A (mm) | B (mm) | C (mm) | $L \geq A + B + C$ (mm) |
|-------------|------------|--------|-------------|--------|---------|-------------------------|
| F04 | R01 | 300 | $300 + 123$ | +30 | $C = 0$ | ≥ 453 |

[Table 6]

• Signal Feedback

0. Standard Limit Switches

Standard MLA-J2 comes with limit switches that automatically shut off motor at the end of travel path.

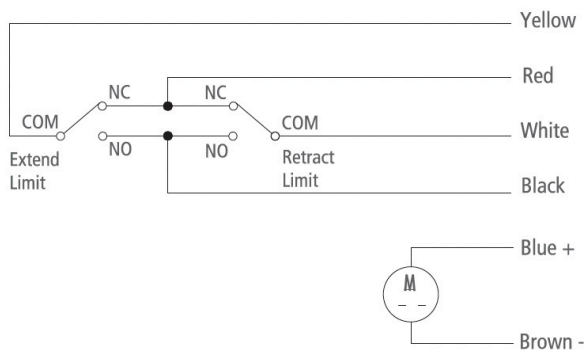


| Wire Type | | |
|-----------|-------|-----|
| | Black | Red |
| Extend | - | + |
| Retract | + | - |

[Table 6]

1. Endstop Signal

The actuator can be equipped with endstop signal output, but it will not auto-stop at either end of travel.



| Wire Type | | |
|-----------|-------|------|
| | Brown | Blue |
| Extend | - | + |
| Retract | + | - |

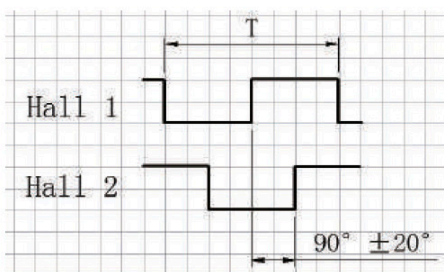
| Signal Wire Coding | |
|--------------------|-------------------------------|
| Black | Extend or Retract Limit, N.O. |
| Red | Extend or Retract Limit, N.C. |
| Yellow | Extend Limit, COM. |
| White | Retract Limit, COM. |

[Table 7]

2. Hall Effect Sensor (Standard Dual-sensor)

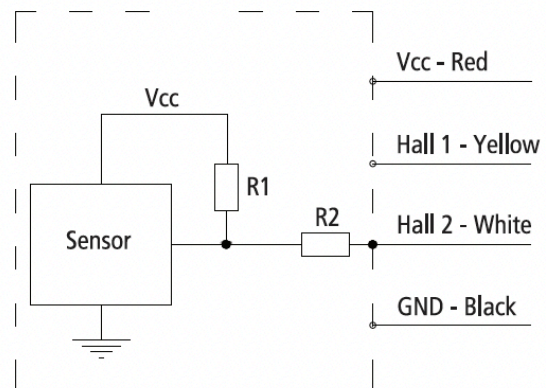
| Code | Pulse Equivalent per Sensor (pulse/mm) | |
|------|--|-------------------------|
| | 1 Pole Pair | 4 Pole Pairs (Standard) |
| A | 10.28 | 41.10 |
| B | 6.53 | 26.10 |
| C | 4.35 | 17.40 |

[Table 8]



Oscillogram

Wire Coding

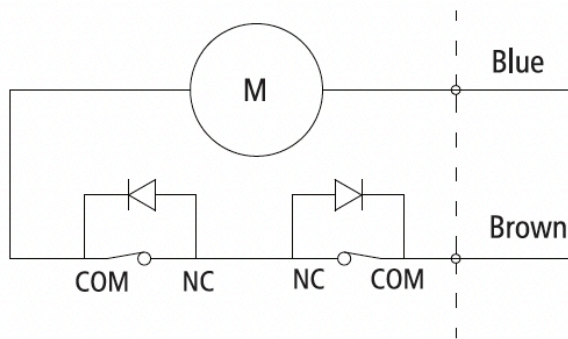


* Power supply (V)= 5~15V

• **Signal Feedback**

2. Hall Effect Sensor (Standard Dual-sensor) - continued

Internal Motor Wiring Diagram



Internal Motor Wiring

3. Reed Switch

Standard N.O. Contact. Optional N.C. Contact.

• Product Inquiry Table

| Selection | Specification | Available Options | | | |
|----------------------|--------------------------|---|------------------------|------------------|-------------------|
| <input type="text"/> | Voltage | 1 = 12V | 2 = 24V | 3 = 36V | 4 = 48V |
| <input type="text"/> | Load and Speed | See [Table 2] | | | |
| <input type="text"/> | Stroke (mm) | Please contact cs@machmo.com if required stroke is out of range. | | | |
| <input type="text"/> | Installation Length (mm) | See [Tables 3-6] | | | |
| <input type="text"/> | Front Mounting End | F01 - F09 | | or FX = Custom | |
| <input type="text"/> | Rear Mounting End | R01 - R04 | | or RX = Custom | |
| <input type="text"/> | Mounting Hole Direction | Front 1 = 90° | Front 2 = 0° | Rear 1 = 90° | Rear 2 = 0° |
| <input type="text"/> | Signal Feedback | 0 = None | 1 = Endstop Signal | 2 = Hall Sensor | 3 = Reed Switches |
| <input type="text"/> | Cable Length | 1 = 500mm | 2 = 1,000mm | 3 = 2,000mm | X = Custom |
| <input type="text"/> | Connector | 0 = Tinned Bare Wires | 1 = Go with KZ Control | X = Custom | |
| <input type="text"/> | Working Temperature | 1 = -10°C ~ 65°C | | 2 = -40°C ~ 65°C | |
| <input type="text"/> | Working Frequency | Estimated Work Cycles Per Day | | | |
| <input type="text"/> | End Use | Indoor or Outdoor? | | | |

Application